IN THE SPECIFICATION

__Kindly replace the paragraph being on line 32 of page 5 and extending to line 10 of page 5 with the following:__

FIG. 1 illustrates an embodiment of how the RSL language may be utilized by an end-user, sitting at a computer terminal, desiring to create a robotic web presentation. FIG. 1 illustrates a snapshot image of a computer terminal display screen 10 running a program for creating a robotic presentation. As shown, A palette of selectable icons [[20]] 05 for defining desired robotic actions are defined in an upper portion of the display screen 10 including a "run" icon 11, "jump" 13, "smile" 15, and so on. The user would create a robotic presentation by simply grabbing and dropping the selectable icons in a desired presentation sequence 35. The snapshot image of FIG. 1 illustrates that the end-user has created a partial robotic web presentation consisting of four icons commanding the robot to first "jump" 36, "smile" 37, sigh" 38 and "roll eyes" 39 in that order as indicated by the time axis. Using the simplified icon driven approach, a robotic presentation may be created in a straight forward easily understood manner.

__Kindly replace the paragraph being on line 16 of page 9 with the following:__

The coding statements (1-7) are supplied to the robot hardware handler [[35]] 45 unit of the robot controller via the distributing unit 34 and are written in the RHWL programming language utilizing an XML embodiment. The construction of the coding statements are known in the art of programming. Of note are statements 3 and 4 which define low-level robotic hardware language statements for directly controlling the actions of a robot. Specifically, RHWL statements (3) and (4) direct the robot 41 to tilt its head 40 degrees and then pan its head by 20 degrees.

__Kindly replace the paragraph being on line 23 of page 9 with the following:__

Also shown in FIG. 2 are video 24 and audio 28 files that may be included in the robotic presentation, coordinated by the distribution unit 24, as an audio [[25]] 58 and

video stream [[29]] 54 to be downloaded as supplementary files to the robot controller 41
for providing video and audio enhancements to the robotic presentation 40.